

KLM spirala

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rezisten im kritenij

a) $T; \quad +$

b) $\frac{1}{2} m v^2 = \frac{1}{2} m (r^2 \dot{\varphi}^2 + \dot{r}^2)$

vezi: $r = a e \quad \dot{r} = a \dot{e}$

$T = \frac{1}{2} m a^2 \dot{\varphi}^2 (1 + e^2) \quad 1/4 \quad \vec{r}, \dot{\vec{r}}$

$a \dot{\varphi} \cos t \rightarrow a \dot{\varphi} \sin t$
 $a \dot{\varphi} (\cos t - \sin t), a \dot{\varphi} (\sin t + \cos t)$
 $a \dot{\varphi}, 0 = (r, \dot{r})$

c) $v_0^2 = a^2 \dot{\varphi}^2 (1 + e^2)$

$\frac{v_0}{a} dt = d\varphi \sqrt{1 + e^2} =$

$\frac{v_0}{a} t = \frac{1}{2} (\varphi \sqrt{1 + e^2} + \arcsinh \varphi) \quad 1/4$

d) multi t: $\frac{v_0 t}{a} = \varphi$
(multi)

reliki t: $\frac{v_0 t}{a} = \frac{1}{2} \varphi^2; \quad \varphi = \sqrt{\frac{2 v_0 t}{a}} \quad 1/4$
(reliki)

e) $L = m r^2 \dot{\varphi} = m a^2 e^2 \dot{\varphi}$

$M = \dot{L} = m a^2 (2 e \dot{\varphi}^2 + e^2 \ddot{\varphi})$

za male t $M = m v_0^2 \frac{2 v_0 t}{a}$

vazlaga $L = m r v \dot{\varphi} =$
 $= m a^2 e \dot{\varphi} \approx m a e^2 v_0$

$L \sim t^2, M \sim t$

za relike t hitrost ima le φ kamp.

$L = m r a \dot{\varphi} = m r v_0 a \sqrt{t}$

$M \sim \frac{1}{\sqrt{t}}$

vrtilna količina se povečuje, ker se
 skica povečuje r , kar \sqrt{t}



$\frac{1}{4} t$

$$f) \quad L = \frac{1}{2} m r^2 (\dot{\varphi} + \dot{\alpha})^2 + \frac{J}{2} \dot{\alpha}^2 + \frac{1}{2} m a^2 \dot{\varphi}^2 \quad \begin{matrix} r = a\varphi \\ \dot{r} = a\dot{\varphi} \end{matrix}$$

$r = a\varphi$ (φ zasuk gledi na spiralu)

$$L = \frac{1}{2} m a^2 \varphi^2 (\dot{\varphi} + \dot{\alpha})^2 + \frac{J}{2} \dot{\alpha}^2 + \frac{1}{2} m a^2 \dot{\varphi}^2$$

$$L \neq L(\alpha)$$

$$\frac{\partial L}{\partial \dot{\alpha}} = \text{konst} = L_z; \quad \begin{matrix} z\text{-komp.} \\ \text{nutikalna količina} \\ 1/4 \end{matrix}$$

$$p_\alpha = \frac{\partial L}{\partial \dot{\alpha}} = m a^2 \varphi^2 (\dot{\varphi} + \dot{\alpha}) + J \dot{\alpha}$$

$$g) \quad \text{zač. pogoraj: } r=0, \dot{\alpha}=0 \Rightarrow p_\alpha=0$$

za male t : r maljen

$$m r^2 \dot{\varphi} + (m r^2 + J) \dot{\alpha} = 0$$

$$\dot{\alpha} = -\frac{m r^2}{m r^2 + J} \dot{\varphi} \approx -\frac{m r^2}{J} \dot{\varphi}$$

$$(T \approx m r^2 \dot{\varphi}^2 \approx \text{konst} \quad \dot{\varphi} \approx 1/r)$$

za velike t : r velik

$$\dot{\alpha} = -\dot{\varphi} \frac{(m r^2 + J)}{m r^2} \approx -\dot{\varphi}$$

palcišji utiši gledanu iz minimijega sistema podaju $\varphi + \alpha$

$$(\varphi + \alpha)' = 0 \quad \varphi + \alpha = \text{konst.}$$

1/4

gibanje r ravnj črti, tigre okoli izherlišje.



3. naloga

več mčimur. Eden od njih:

$$L = \dot{q}^m f(q)$$

$$\dot{L} = \frac{\partial L}{\partial \dot{q}} \frac{d\dot{q}}{dt} + \frac{\partial L}{\partial q} \frac{dq}{dt}$$

⇓

zagrnjene en.

$$= \frac{\partial L}{\partial \dot{q}} \frac{d\dot{q}}{dt} + \left(\frac{d}{dt} \frac{\partial L}{\partial \dot{q}} \right) \frac{dq}{dt}$$

$$= \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \dot{q} \right) = \frac{d}{dt} (m \dot{q}^m f(q)) = \frac{d}{dt} (m L)$$

en L oblike zgoraj

$$\dot{L} = m \dot{L}; \text{ če } m \neq 1 \text{ ima rezultat le en } \dot{L} = 0$$

QED.

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