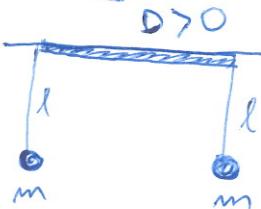


## TORZIJSKO

## SKLOPLJENI TEŽNI

## NIHALI

Imamo dve mihali, ki mihata pravokotno okrog skupne osi, ki deluje nuratost torzija silopitev z velikostjo D. Poisci stacionarne mihanja okrog njih!



Sistem opisemo z odmiku  
 $\Phi = \begin{pmatrix} \varphi_1 \\ \varphi_2 \end{pmatrix}$

Kinetična energija:

$$T = \frac{1}{2} m l^2 (\dot{\varphi}_1^2 + \dot{\varphi}_2^2)$$

Potencialna energija:

$$V = -mgl (\cos\varphi_1 + \cos\varphi_2) + \frac{D}{2} (\varphi_1 - \varphi_2)^2 = -mgl (\cos\varphi_1 + \cos\varphi_2 + \frac{D}{2} (\varphi_1 - \varphi_2)^2)$$

Ravnovesne legi:

$$\left. \frac{\partial V}{\partial \varphi_1} \right|_{\varphi_0} = +mgl (\sin\varphi_{10} + \frac{D}{l} (\varphi_{10} - \varphi_0)) = 0 \quad (1)$$

in hkrati:

$$\left. \frac{\partial V}{\partial \varphi_2} \right|_{\varphi_0} = mgl (\sin\varphi_{20} + \frac{D}{l} (\varphi_{20} - \varphi_0)) = 0 \quad (2)$$

$$(1) + (2) : mgl (\sin\varphi_{10} + \sin\varphi_{20}) = 0 \Rightarrow \sin\varphi_{10} = -\sin\varphi_{20} \Rightarrow \varphi_{10} = \varphi_{20}$$

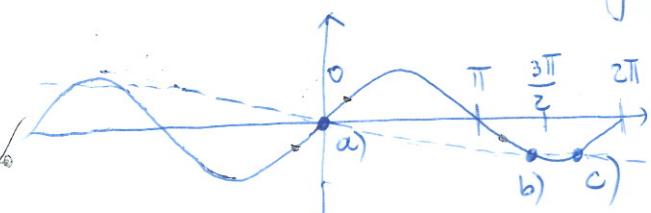
$$(1) - (2) : mgl (\sin\varphi_{10} - \sin\varphi_{20} + \frac{2D}{l} (\varphi_{10} - \varphi_{20})) = 0 \Rightarrow \sin\varphi_{10} = -2\frac{D}{l} \varphi_{10}$$

Mi si izberemo & posrite zah=0  $\Rightarrow \varphi_{10} = -\varphi_{20}$   
 $\sin\varphi_{10} = -2\frac{D}{l} \varphi_{10}$

To enako moramo graficno rešiti:

graficno

rešiti:

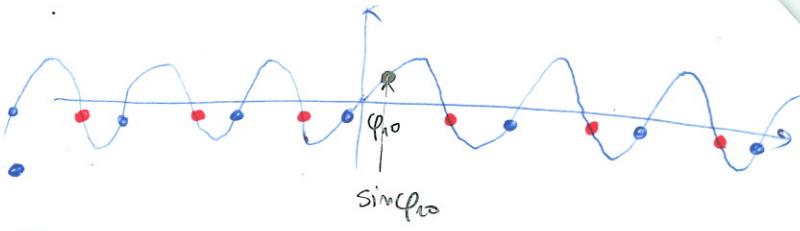


In možne rešitve

(razen če malom z prevelike potem le 1, nezemljivo - ko presibka D).

$$\varphi_{10} - \sin \varphi_{10} = -\sin \varphi_{20}$$

Mozne resite:  $\varphi_{10} = \begin{cases} -\varphi_{20} + 2\pi m \\ +\varphi_{20} + \pi + 2\pi m \end{cases}$



To ustavimo v

$$① - ②: m \omega (\sin \varphi_{10} - \sin \varphi_{20} + 2\pi (\varphi_{10} - \varphi_{20})) = 0$$

$$a) \left\{ \begin{array}{l} 2 \sin \varphi_{10} + 4\pi \varphi_{10} - 2\pi m = 0 \\ 2 \sin \varphi_{20} + 4\pi \varphi_{20} - 2\pi m = 0 \end{array} \right.$$

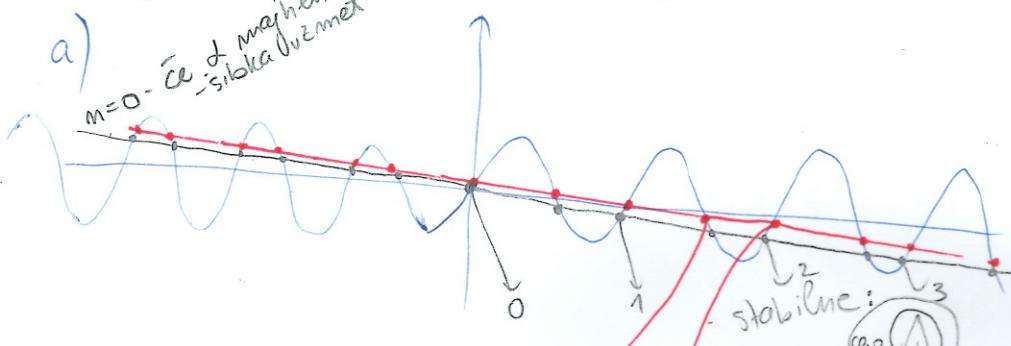
$$b) \left\{ \begin{array}{l} 2 \sin \varphi_{10} + 4\pi \varphi_{10} - 2\pi m - \pi/2 = 0 \\ 2 \sin \varphi_{20} + 4\pi \varphi_{20} - 2\pi m - \pi/2 = 0 \end{array} \right.$$

$$\sin \varphi_{10} = 2\pi m + \frac{\pi}{2}$$

trirezitev

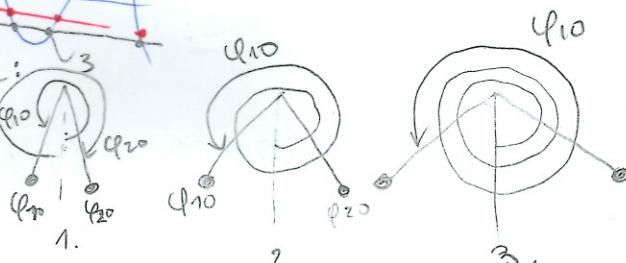
Mnogo rešitev za  $\varphi_{10}$ !

a)  $m=0$  - če je majhen sibka rezitev

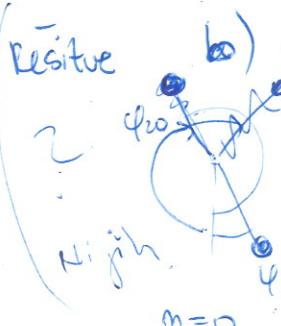


labilna  
stabilna,  
isti kot kot pri  
 $m=0$ , ista rezitev!

$m=1, 2, 3, \dots$  Dajo iste reziteve  
kot  $\varphi_{20}$  sta  $m=0$ , le oba  $\varphi_{10}$  im pač za par slupnih zasukov zasukana. Kar je pa itak vseeno.



čiprav ovjeta vseeno se užezi ogromno krog izhodišča, je to stacionarna krog se vedno dolgor.



$$\varphi_{10} = +\varphi_{20} + \pi + 2\pi m \text{ so zanimive, saj so take!}$$



Preveniti moramo, katerje so stabilne: Pogoj za stabilnost je  $V(\underline{\varphi}_0 + \delta \underline{\varphi}) > V(\underline{\varphi}_0)$  za v bližnji okolici  $\underline{\varphi}_0$ -stacionarne legi. Če razvijemo v Taylorjevo vrsto, se to prevede na pogoj:

$$V(\underline{\varphi}_0 + \delta \underline{\varphi}) = V(\underline{\varphi}_0) + \underbrace{\sum_i \frac{\partial V}{\partial \varphi_i} \delta \varphi_i}_{\text{O}} + \frac{1}{2} \sum_{ij} \frac{\partial^2 V}{\partial \varphi_i \partial \varphi_j} \delta \varphi_i \delta \varphi_j + \dots$$

$$= V(\underline{\varphi}_0) + \frac{1}{2} \delta \underline{\varphi}^\top \tilde{V} \delta \underline{\varphi}; \quad \tilde{V}_{ij} = \frac{\partial^2 V}{\partial \varphi_i \partial \varphi_j}$$

$\Rightarrow \underline{\varphi}_0$  je stabilna, če je  $\tilde{V} \delta \underline{\varphi}^\top \tilde{V} \delta \underline{\varphi} > 0$ . - če je  $\tilde{V}$  pozitivno definitna.

Kako to preventi?

$\rightarrow$  Če zapeč diagonaliziramo  $\tilde{V}$  (kar se da, ker je realna in simetrična, torej hermitska), je  $\tilde{V} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$ . Da imamo  $\det \tilde{V} > 0$  in  $\text{Tr } \tilde{V} > 0$ , to preventimo:

$$\textcircled{3} \quad \text{Tr } \tilde{V} = \frac{\partial^2 V}{\partial \varphi_1^2} \Big|_{\underline{\varphi}_0} + \frac{\partial^2 V}{\partial \varphi_2^2} \Big|_{\underline{\varphi}_0} = \cancel{mgl} (\cos \varphi_{10} + 2 + \cos \varphi_{20} + 2) = \cancel{mgl} 2(\cos \varphi_{10} + 2) > 0$$

$$\textcircled{4} \quad \text{Det } \tilde{V} = \frac{\partial^2 V}{\partial \varphi_1^2} \Big|_{\underline{\varphi}_0} \cdot \frac{\partial^2 V}{\partial \varphi_2^2} \Big|_{\underline{\varphi}_0} - \left( \frac{\partial^2 V}{\partial \varphi_1 \partial \varphi_2} \right)^2 \Big|_{\underline{\varphi}_0} = \cancel{(mgl)^2} \left( (\cos \varphi_{10} + 2)(\cos \varphi_{20} + 2) - (-2)^2 \right) > 0$$

$$\Rightarrow \textcircled{3} \quad \cos \varphi_{10} + 2 > 0$$

$$\textcircled{4} \quad \cos \varphi_{10}^2 + 2 \cos \varphi_{10} > 0$$

Prevenimo tri stacionarne legi:

a)  $\Phi \varphi_{10} = 0$  :  $\textcircled{3} \Rightarrow 2 > 0 \checkmark$

$$\textcircled{4} = 1 + 2 \cdot 2 > 0 \checkmark$$

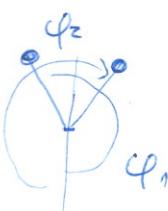
stabilna

$$\bullet \quad \varphi_1 = \varphi_2$$

b)  $\varphi_{10} \in [\pi, \frac{3\pi}{2}]$ :  $\textcircled{3} = -1 \cos \varphi_{10} + 2$

$$\textcircled{4} = |\cos \varphi_{10}|^2 - 2 \cdot 1 \cos \varphi_{10} \neq$$

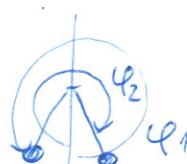
če  $\textcircled{3} > 0$ :  $|\cos \varphi_{10}| < 2$ , potem  $\textcircled{4} = |\cos \varphi_{10}| (1 \cos \varphi_{10} - 2) < 0$  obratno.  
Prav tako  $\Rightarrow$  labilna!



c)  $\varphi_{10} \in [\frac{3\pi}{2}, 2\pi]$ :  $\textcircled{3} = 1 \cos \varphi_{10} + 2 > 0 \checkmark$

$$\textcircled{4} = |\cos \varphi_{10}| (1 \cos \varphi_{10} + 2) > 0 \checkmark$$

$\Rightarrow$  stabilna



(2)

Iz slice rešitev:  vidimo, da rešitev c) vstopa, le če  $f(\varphi_{10}) = -2 \cos \varphi_{10} \quad \vee \varphi_{10} = \frac{3\pi}{2}$  večja od  $\sin \varphi_{10}$ .  
 $-2 \cos \frac{3\pi}{2} > \sin \frac{3\pi}{2} = -1 \Rightarrow \lambda < \frac{1}{3\pi}$ .

### Razvoj drugih stabilnih leg:

$$\varphi_1 = \varphi_{10} + \delta\varphi_1$$

$$\varphi_2 = \varphi_{20} + \delta\varphi_2$$

$$\underline{\delta\varphi} = \begin{pmatrix} \delta\varphi_1 \\ \delta\varphi_2 \end{pmatrix}$$

Razviti moramo do 2. reda.

-Potencial smo že:

$$V = V(\varphi_0) + \frac{1}{2} \underline{\delta\varphi}^\top \underline{\underline{V}} \underline{\delta\varphi} ; \quad \underline{\underline{V}} = \cancel{mgl} \begin{pmatrix} \cos \varphi_{10} + 2 & -2 \\ -2 & \cos \varphi_{10} + 2 \end{pmatrix}$$

### Kinetična energija

$$\underline{T} = \frac{ml^2}{2} (\dot{\varphi}_1^2 + \dot{\varphi}_2^2) = \cancel{\frac{ml^2}{2}} \underline{\dot{\varphi}}^\top \underline{\underline{T}} \underline{\dot{\varphi}} ; \quad \underline{\underline{T}} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \frac{ml^2}{4}$$

### Izhangje lastnih mihanj:

$$\underline{\dot{\varphi}} = \underline{\varphi}_0 \underline{a} e^{-i\omega t}$$

$$\underline{\underline{V}} \underline{a} = \omega^2 \underline{\underline{T}} \underline{a} \Rightarrow \det(\underline{\underline{V}} - \omega^2 \underline{\underline{T}}) = 0 \quad \sum_j \tilde{T}_{ij} \tilde{\varphi}_j + \sum_j \tilde{V}_{ij} \varphi_j = 0$$

$$\cancel{mgl} \left( \begin{pmatrix} \cos \varphi_{10} + 2 & -2 \\ -2 & \cos \varphi_{10} + 2 \end{pmatrix} - \underbrace{\omega^2 \frac{ml^2}{4} \cancel{mgl}}_{\lambda} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right) \underline{a} = 0$$

$$\det \left( \begin{pmatrix} \cos \varphi_{10} + 2 - \lambda & -2 \\ -2 & \cos \varphi_{10} + 2 - \lambda \end{pmatrix} \right) = 0 \quad \lambda = \omega^2 / \omega_0^2 ; \quad \omega_0^2 = g/l$$

$$\Rightarrow (\cos \varphi_{10} + 2 - \lambda)^2 - \lambda^2 = 0$$

$$\Rightarrow \cos \varphi_{10} + 2 - \lambda_{\pm} = \pm \lambda$$

$$\Rightarrow \lambda_{1,2} = \pm \cos \varphi_{10} + 2 \quad \Rightarrow \quad \lambda_1 = +\cos \varphi_{10} \\ \lambda_2 = +\cos \varphi_{10} + 2\lambda$$

Lastni frekvenci mihanj sta:

$$\omega_1 = \sqrt{\lambda_1 \omega_0^2} = \sqrt{\cos \varphi_{10}} \omega_0 ; \quad \omega_2 = \sqrt{\cos \varphi_{10} + 2\lambda} \omega_0$$

### Lastni velotorji:

$$\lambda_1: \begin{pmatrix} +2 & -2 \\ -2 & +2 \end{pmatrix} \begin{pmatrix} a_{11} \\ a_{12} \end{pmatrix} = 0 \Rightarrow \begin{pmatrix} a_{11} \\ a_{12} \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$



$$\lambda_2: \begin{pmatrix} -2 & -2 \\ -2 & -2 \end{pmatrix} \begin{pmatrix} a_{21} \\ a_{22} \end{pmatrix} = 0 \Rightarrow \begin{pmatrix} a_{21} \\ a_{22} \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

