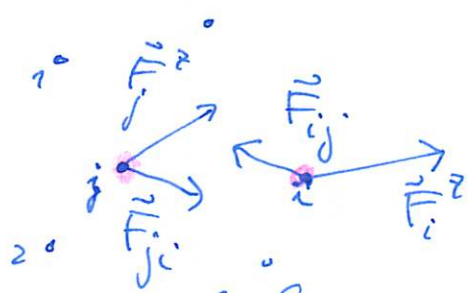


# Sistem N točkovitih teles

N točkovitih teles, za vsako logično rešeno Newtonovo zbirano, za vsako par  $\vec{F}_{ij} = -\vec{F}_{ji}$ .



$$\vec{F}_i^z + \sum_{j \neq i} \vec{F}_{ij} \quad \text{nila na } i$$

## Gibalna količina sistema

$$\left. \begin{aligned} m_1 \vec{a}_1 &= \vec{F}_1^z + \vec{F}_{12} + \sum_{j>2} \vec{F}_{1j} \\ m_2 \vec{a}_2 &= \vec{F}_2^z + \vec{F}_{21} + \sum_{j>3} \vec{F}_{2j} \\ \vdots \\ \sum_{i=1}^N m_i \vec{a}_i &= \underbrace{\sum_i \vec{F}_i^z}_{\vec{F}^z} + \underbrace{\vec{F}_{12} + \vec{F}_{21}}_0 + \underbrace{\sum_{i,j \neq i} \vec{F}_{ij}}_{\sum_i \sum_{j<i} \vec{F}_{ij} + \vec{F}_{ji}} \end{aligned} \right\} +$$

$$\vec{p} \stackrel{\text{def}}{=} \sum_i \vec{p}_i$$

$$\dot{\vec{p}} = \vec{F}^z$$

$\vec{F}^z = 0 \Rightarrow \vec{p} = \vec{p}_0 = \text{konst.}$

Težnja

$$M \vec{r}_T = \sum_i m_i \vec{r}_i \quad ; \quad M = \sum_i m_i$$

$$\vec{p} = \sum_i m_i \vec{v}_i = M \dot{\vec{r}}_T = M \vec{v}_T \quad \text{hitrost težnje}$$

izgleda kot Newtonovo zbirano z vse skupaj;

$$M \vec{a}_T = M \ddot{\vec{r}}_T = M \dot{\vec{v}}_T = \dot{\vec{p}} = \vec{F}^z$$

pozor: uporaba tega s pramisljenom.

opr.: zbiraj helosa poravnajo avto?  
sila težnja; efektivno nil podsystemov

## .. Vektorska količina sistema

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$$\vec{L} = \sum_i \vec{l}_i = \sum_i \vec{r}_i \times \vec{p}_i$$

$$\dot{\vec{L}} = \sum_i \frac{d}{dt} (\vec{r}_i \times \vec{p}_i) = \sum_i \underbrace{\dot{\vec{r}}_i \times m \vec{v}_i}_0 + \sum_i \vec{r}_i \times m \dot{\vec{a}}_i$$

$$\dot{\vec{L}} = \sum_i \vec{r}_i \times \vec{F}_i^z + \sum_{j \neq i} \vec{r}_i \times \vec{F}_{ij} = \vec{M}^z + \vec{M}^m = \vec{M}$$

ponovno simetričnom rešetom

$$\sum_{\substack{i \\ j \neq i}} \vec{r}_i \times \vec{F}_{ij} = \sum_{\substack{i \\ j < i}} (\vec{r}_i \times \vec{F}_{ij} + \vec{r}_j \times \vec{F}_{ji}) =$$

$$= \sum_{\substack{i \\ j < i}} (\vec{r}_i - \vec{r}_j) \times \vec{F}_{ij} = \vec{M}^m$$

Če su sile centralne,  $\vec{F}_{ij} = F_{ij} \frac{\vec{r}_i - \vec{r}_j}{|\vec{r}_i - \vec{r}_j|}$ ,  $\vec{M}^m = 0$ .

To ne valja za magnetsko sile; upr. za sile međ. magnetnim dipolima.

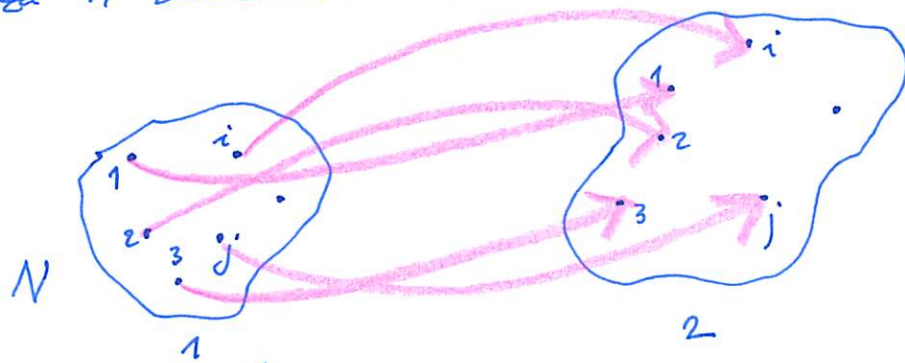
Valja točnije

$$\dot{\vec{L}} = \vec{M}^z, \quad \vec{M}^z = \sum_i \vec{r}_i \times \vec{F}_i^z$$

$$\text{Če } \vec{M}^z = 0 \Rightarrow \underline{\vec{L} = \vec{L}_0 = \text{konst.}}$$

∴ Energija sistema N teles

v listu ponovimo našo končno list za 1 delec ...



- delo sile

$$A = \sum_i \int_{t_1}^{t_2} \vec{F}_i \cdot d\vec{r}_i = A^z + A^m$$

$$A^z = \sum_{i_1} \int_{pot i} \vec{F}_{i_1}^z \cdot d\vec{r}_i \quad A^m = \sum_{j \neq i} \int_{pot i} \vec{F}_{ij} \cdot d\vec{r}_i$$

enako kot prej

$$A = \sum_i \int_{t_1}^{t_2} m_i \cdot \underbrace{\dot{\vec{v}}_i}_{\frac{d\vec{v}_i}{dt}} \cdot \vec{v}_i \cdot dt = \int_{t_1}^{t_2} \left( \frac{d}{dt} \sum_i \frac{1}{2} m_i v_i^2 \right) dt =$$

$$= T(t_2) - T(t_1) = \Delta T$$

- kinetična energija sistema

$$T = \frac{1}{2} \sum_i m_i v_i^2$$

$$\vec{v}_i = \vec{v}_T + \vec{v}_i'$$

$$T = \frac{1}{2} \sum_i m_i (\vec{v}_T + \vec{v}_i') \cdot (\vec{v}_T + \vec{v}_i') =$$

$$= \frac{1}{2} \sum_i m_i (v_T^2 + v_i'^2 + 2 \vec{v}_i' \cdot \vec{v}_T) =$$

$$= \frac{1}{2} M v_T^2 + \frac{1}{2} \sum_i m_i v_i'^2 + \underbrace{\vec{v}_T \cdot \sum_i m_i \vec{v}_i'}_0$$

translacijska  
težišča

glede na  
težišče = rotacija

$$\underbrace{\vec{v}_i - \vec{v}_T}_{\vec{v}_i'} \cdot \underbrace{\sum_i m_i \vec{v}_i'}_{M \vec{v}_T - M \vec{v}_T} = 0$$



mej meja

$$\vec{F}_i^z = -\nabla_i U_i^z(\vec{r}_i)$$

$$\int_{\vec{r}_{i2}}^{\vec{r}_{i1}} \vec{F}_i^z \cdot d\vec{r}_i = -\int_{\vec{r}_{i2}}^{\vec{r}_{i1}} \nabla_i U_i^z(\vec{r}_i) \cdot d\vec{r}_i = -U_i^z(\vec{r}_{i2}) + U_i^z(\vec{r}_{i1})$$

$$A^z = \sum_i \int \vec{F}_i^z \cdot d\vec{r}_i = -U(t_2) + U(t_1) = -\Delta U^z$$

$$U^z = \sum_i U_i^z(\vec{r}_i) \Big|_{t=\dots}$$

za "notenje" sile predpostavimo, da so tudi potencialne (gravitacijske, elektromagn.) in centralne

$$V_{ij} = V_{ij}(\vec{r}_{ij}) = V_{ij}(|\vec{r}_{ij}|); \quad \vec{r}_{ij} = \vec{r}_i - \vec{r}_j$$

$$= V_{ji}$$

$$A^m = \sum_{j < i} \left( \int \vec{F}_{ij} \cdot d\vec{r}_i + \int \vec{F}_{ji} \cdot d\vec{r}_j \right) =$$

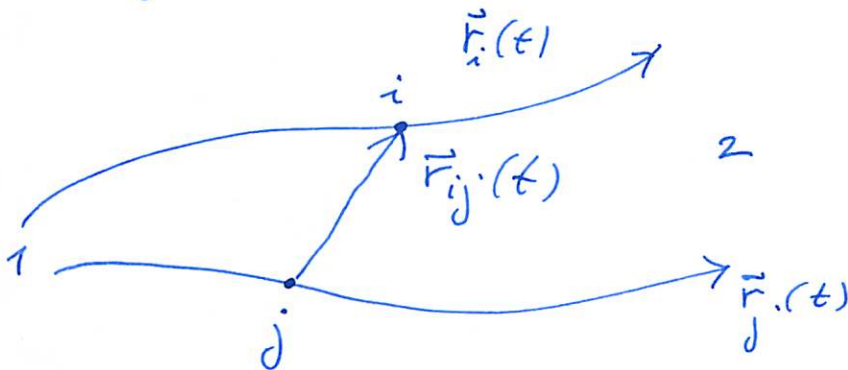
$$= \sum_{\substack{i \\ j < i}} \int \vec{F}_{ij} \cdot d\vec{r}_{ij}$$

kde je  $A^m = ?$

$$\cdot F \perp dr$$

$$\cdot F = 0$$

$$\cdot dr = 0$$



$$\vec{F}_{ij} = -\nabla_{ij} V_{ij}(\vec{r}_{ij}) = -\left( \frac{\partial}{\partial r_i} V_{ij}(\vec{r}_{ij}), \frac{\partial}{\partial y_i}, \dots, \frac{\partial}{\partial z_i} \dots \right)$$

gradient centralnega potenciala  
 $V = V(|\vec{r}|) = V(r) ; r = \sqrt{x^2 + y^2 + z^2}$

$$\nabla V(r) = \left( \frac{\partial}{\partial x} V, \frac{\partial}{\partial y} V, \frac{\partial}{\partial z} V \right) = \left( \frac{\partial V(r)}{\partial r} \frac{\partial r}{\partial x}, \frac{\partial V(r)}{\partial r} \frac{\partial r}{\partial y}, \frac{\partial V(r)}{\partial r} \frac{\partial r}{\partial z} \right) = \frac{\partial V}{\partial r} \nabla r$$

$$\nabla r = \left( \frac{\partial}{\partial x} \sqrt{x^2 + y^2 + z^2}, \frac{\partial}{\partial y} \sqrt{x^2 + y^2 + z^2}, \frac{\partial}{\partial z} \sqrt{x^2 + y^2 + z^2} \right) = \left( \frac{1 \cdot 2x}{2\sqrt{x^2 + y^2 + z^2}}, \frac{2y}{2r}, \frac{z}{r} \right) = \frac{\vec{r}}{r}$$

$$\nabla V(r) = \frac{\partial V(r)}{\partial r} \frac{\vec{r}}{r}$$

toraj,

$$\vec{F}_{ij} = - \frac{\partial V_{ij}(r_{ij})}{\partial r_{ij}} \frac{\vec{r}_{ij}}{r_{ij}}$$

delo notranjih sil je toraj,

$$A^m = - \sum_{\substack{i \\ j < i}} \int_{r_{ij}^1}^{r_{ij}^2} \nabla_{ij} V_{ij}(r_{ij}) \cdot d\vec{r}_{ij} = - \sum_{\substack{i \\ j < i}} \int \left( \frac{\partial}{\partial x_i} V_{ij} dx_i + \dots \right) =$$

$$= -U^m(t_2) + U^m(t_1), = -\Delta U^m$$

$$U^m = \sum_{\substack{i \\ j < i}} V_{ij}(r_{ij}) = \frac{1}{2} \sum_{ij} V_{ij}(r_{ij})$$

celotna mehanska energija  $W = T + \underbrace{U^z + U^m}_U$

$$A = \underbrace{A^z}_{-\Delta U} + A^m = \Delta T \Rightarrow \Delta W = 0 = \Delta T + \Delta U$$

$W = W_0 = \text{const.}$

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Viriální theorem (Clausius;  $m_1, m_2, \dots, m_N = m_0$ ) <sup>14a</sup>

Zořmenno z N. zolecovou z N telos;  $i=1, \dots, N$ :

$$m_i \ddot{\vec{r}}_i = \sum_{\substack{j \\ j \neq i}} \vec{F}_{ij} + \vec{F}_i^{\text{ext}} \quad / \cdot \vec{r}_i; \sum_i$$

\* 
$$\sum_{\substack{ij \\ j \neq i}} m_i \ddot{\vec{r}}_i \cdot \vec{r}_i = \sum_{\substack{ij \\ j \neq i}} \vec{F}_{ij} \cdot \vec{r}_i + \sum_i \vec{F}_i^{\text{ext}} \cdot \vec{r}_i$$

pomocný rovník:

a) 
$$\frac{d^2}{dt^2} \sum_i m_i \vec{r}_i^2 = \frac{d}{dt} (2 \sum_i m_i \vec{r}_i \cdot \dot{\vec{r}}_i) = 2 \underbrace{2 \sum_i \frac{1}{2} m_i \dot{\vec{r}}_i^2}_{2T} + 2 \underbrace{\sum_i m_i \dot{\vec{r}}_i \cdot \ddot{\vec{r}}_i}_*$$

b) Če  $\vec{F}_{ij} = -\vec{F}_{ji}$ , velja

$$\sum_{\substack{ij \\ j \neq i}} \vec{F}_{ij} \cdot \vec{r}_i = \frac{1}{2} \sum_{\substack{ij \\ j \neq i}} (\underbrace{\vec{F}_{ij} + \vec{F}_{ji}}_{-\vec{F}_{ji}}) \cdot \vec{r}_i = \frac{1}{2} \sum_{\substack{ij \\ j \neq i}} \vec{F}_{ij} \cdot (\vec{r}_i - \vec{r}_j)$$

$i \leftrightarrow j: -\vec{F}_{ij} \cdot \vec{r}_j$

$$= \frac{1}{2} \sum_{\substack{ij \\ j \neq i}} \vec{F}_{ij} \cdot \vec{r}_{ij} \quad \vec{r}_{ij} = \vec{r}_i - \vec{r}_j$$

za neprej:

$$\sum_{\substack{ij \\ j \neq i}} \equiv \sum_{j \neq i}$$

$$\text{in } \sum_{\substack{ij \\ j < i}} \equiv \sum_{j < i}$$

}  $\frac{1}{2} \sum_{\substack{ij \\ j \neq i}} = \sum_{j < i}$



e)  $\vec{F}_{ij}(\vec{r}_{ij}) = -\nabla_{ij} V_{ij}(\vec{r}_{ij}) = -\frac{\partial V_{ij}}{\partial \vec{r}_{ij}} \vec{r}_{ij}$

Sedaj zapišemo a, b in c in m.

$$\frac{d^2}{dt^2} \sum_i \frac{m_i \vec{r}_i^2}{2} = 2T - \frac{1}{2} \sum_{j \neq i} \frac{\partial V_{ij}}{\partial r_{ij}} \frac{\vec{r}_{ij}}{r_{ij}} \cdot \vec{r}_{ij} + \sum_i \vec{F}_i^z \cdot \vec{r}_i$$

Pomnožimo zredaj po času,

$$\vec{f} = \frac{1}{T} \int_0^T f(t) dt,$$

$$\frac{1}{T} \int_0^T \frac{d^2}{dt^2} \sum_i \frac{m_i \vec{r}_i^2}{2} dt = \frac{1}{T} \left. \frac{d}{dt} \sum_i \frac{m_i \vec{r}_i^2}{2} \right|_0^T = \frac{1}{T} \sum_i m_i \vec{r}_i \cdot \dot{\vec{r}}_i \Big|_0^T$$

$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_i m_i \vec{r}_i \cdot \dot{\vec{r}}_i = 0$ , če  $\vec{r}_i \cdot \dot{\vec{r}}_i \Big|_0^T$  ne ostane konstantno (omejeno gibanje).

Torej

$$2\bar{T} = \frac{1}{2} \sum_{j \neq i} \frac{\partial V_{ij}}{\partial r_{ij}} \frac{\vec{r}_{ij}}{r_{ij}} \cdot \vec{r}_{ij} - \sum_i \vec{F}_i^z \cdot \vec{r}_i$$

to je Virialni teorem

primer:  $V(\vec{r}) = \alpha r^n$  in delci potujejo omejeno

$$2\bar{T} = \frac{1}{2} \sum_{j \neq i} n \alpha r_{ij}^{n-1} r_{ij} - \sum_i \vec{F}_i^z \cdot \vec{r}_i$$

$$= \sum_{j < i} n \alpha r_{ij}^n \cdot 2 = \sum_{j < i} n \alpha r_{ij}^n = n V(\vec{r}_{ij})$$

= 0, če npr. delci (plim) v shteti in ne teče v pospej = 0 (Reno-dond) ali pa, če  $\vec{F}_i^z = 0$ .

torej  $2\bar{T} = n\bar{V}$

$$V = \sum_{j < i} V_{ij}$$