

KLM mala nihanja

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1. Ponovi izpeljavo matričnega opisa enačb za mala nihanja, zapiši njihovo rešitev v obliki lastnih nihajnih načinov! Pokaži, da velja posplošena ortogonalnostna relacija med vektorji amplitud odmikov! Zapiši Lagrangeovo funkcijo z uporabo normalnih koordinat!
2. Na vodoravno nameščeno ravno vodilo namestimo zaporedno 3 uteži z masami m, m', m in jih spnemo z vzmetema z enakima koeficientoma k , dolžina neraztegnjene vzmeti l . Uteži po vodilu gladko drsijo. Izračunaj lastne nihajne načine, lastne frekvence! Zapiši Lagrangeovo funkcijo v normalni obliki! Zapiši položaj uteži ob kasnejših časih, če ob $t=0$ prvo maso sunemo, tako da ima hitrost v_0 ! Koliko energije je shranjeno v posamičnih nihajnih načinih? Preveri, da je vsota energij enaka začetni energiji!

1. Sistem opisan s z_1, \dots, z_N . Potencial $V(\underline{z})$.
Razvijemo okrog ekstremna (za mala nihanja minimuma potenciala) pri \underline{z}^0

$$z_i = z_i^0 + \eta_i$$

$$V = V_0 + \frac{1}{2} \sum_{ij} \underbrace{\frac{\partial^2 V}{\partial z_i \partial z_j}}_{V_{ij}} \bigg|_{\underline{z}=\underline{z}^0} \eta_i \eta_j + \dots$$

$$V = \frac{1}{2} \underline{\eta}^T \underline{V} \underline{\eta}$$

kin. energija za male η

$$T = \frac{1}{2} \underline{\dot{\eta}}^T \underline{T} \underline{\dot{\eta}} \quad \begin{matrix} m_1 & & \\ & 0 & \\ & & m_2 \end{matrix} \quad \begin{pmatrix} m_1 & \\ & m_2 \end{pmatrix}$$

lahko pa tudi bolj kompak. u. vedno

$\underline{T}, \underline{V}$ simetrični, poz. definitni.

$$L = T - V$$

$$\underline{T} \ddot{\underline{\eta}} + \underline{V} \underline{\eta} = 0$$

naštrnek $\underline{\eta} = \underline{\eta}^0 e^{-i\omega t}$

$$\left(-\omega^2 \underline{T} + \underline{V} \right) \underline{\eta}^0 = 0 \quad ; \quad \text{posplošen problem l.v.}$$

$$\det \left(-\omega^2 \underline{T} + \underline{V} \right) = 0 \quad \dots \quad \omega^2 \dots \text{lastne frekv.}$$

x. v.

$$\det(-\omega^2 \underline{T} + \underline{V}) = 0 \dots \omega^2 \dots \text{lastna frekv.}$$

$$(-\omega_m^2 \underline{T} + \underline{V}) \underline{a}_m = 0 \quad m\text{-ti l. vektor}$$

Splajne rešitev:

$$\underline{q}(t) = \text{Re} \sum_i \underline{a}_i \begin{cases} d_i e^{-i\omega_i t} & ; \omega_i > 0 \\ c_i + \bar{c}_i t & ; \omega_i = 0 \end{cases}$$

Zač. pogoji $\underline{q}(t=0) = \dots \quad \dot{\underline{q}}(t=0) = \dots$

Velja prop. ortog.:

$$\underline{a}_i^T \underline{T} \underline{a}_j = J_{ij} \quad (\text{l. v.}, \text{ ki pripadaja}$$

različnim ω in so ortog.)

lahko izberemo normo

tako, da $\underline{a}_i^T \underline{T} \underline{a}_i = 1$

$$D.: \underline{a}_i^T / \omega_j^2 \underline{T} \underline{a}_j = \underline{V} \underline{a}_j \quad (1)$$

$$\omega_i^2 \underline{a}_i^T \underline{T} = \underline{a}_i^T \underline{V} \quad / \underline{a}_j^{(2)} \quad (1)-(2)$$

$$(\omega_i^2 - \omega_j^2) \underline{a}_i^T \underline{T} \underline{a}_j = 0$$

normalna oblika:

normalne koval

$$\underline{q} = \sum_i d_i(t) \underline{a}_i$$

$$L = \frac{1}{2} \sum_{ij} \dot{d}_i \dot{d}_j \underbrace{\underline{a}_i^T \underline{T} \underline{a}_j}_{J_{ij}} - \frac{1}{2} \sum_{ij} d_i d_j \underbrace{\underline{a}_i^T \underline{V} \underline{a}_j}_{\omega_i^2 J_{ij}}$$

$$L = \frac{1}{2} \sum_i (\dot{d}_i^2 - \omega_i^2 d_i^2) \quad L \text{ izražen v}$$

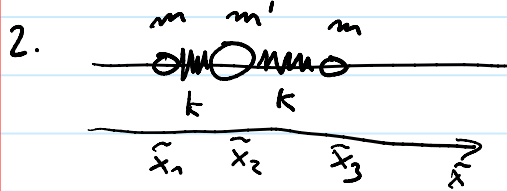
norm. obliki

energija $E = \frac{1}{2} (\dot{d}_i^2 + \omega_i^2 d_i^2) = \sum_i E_i$

$$d_i = d_{i0} \cos \omega_i t \quad E_i = \frac{1}{2} d_{i0}^2 \omega_i^2 \quad ; \omega_i \neq 0$$

$$d_i = d_{i0} \cos \omega t \quad E_i = \begin{cases} \frac{1}{2} d_{i0}^2 \omega_i^2 & ; \omega_i \neq 0 \\ \frac{1}{2} d_{i0}^2 \omega^2 & ; \omega_i = 0 \end{cases}$$

energija v i-tem nih. načinu.



$$\tilde{x}_1 = x_{10} + x_1 \quad \tilde{x}_2 = x_{20} + x_2 \quad \tilde{x}_3 = x_{30} + x_3$$

$$= x_{10} + l + x_2$$

$$\tilde{x}_1 < \tilde{x}_2 < \tilde{x}_3$$

$$V = \frac{k(\tilde{x}_2 - \tilde{x}_1 - l)^2}{2} + \frac{k(\tilde{x}_3 - \tilde{x}_2 - l)^2}{2}$$

raztezek / skrček vzame ti
glede na
neraztegnjen

$$V = \frac{k(x_2 - x_1)^2}{2} + \frac{k}{2}(x_3 - x_2)^2$$

potencial je v kvadr. obliki

$$T = \sum_i \frac{m_i \dot{x}_i^2}{2}$$

$$V = \frac{1}{2} k (x_1^2 + x_2^2 - 2x_1x_2 + x_3^2 + x_2^2 - 2x_2x_3)$$

$$\underline{\underline{T}} = \begin{bmatrix} m & & \\ & m' & \\ & & m \end{bmatrix}$$

$$\underline{\underline{V}} = k \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}$$

$$\left(-\omega^2 \underline{\underline{T}} + \underline{\underline{V}} \right) \underline{a}_i = 0$$

2. načina: direktno

$$\det \begin{pmatrix} -\omega^2 m + k & -k & 0 \\ -k & -\omega^2 m' + 2k & -k \\ 0 & -k & -\omega^2 m + k \end{pmatrix} = 0$$

$$(-\omega^2 m + k) [(-\omega^2 m + k)(-\omega^2 m' + 2k) - k^2] + k(-k(-\omega^2 m + k)) = 0$$

$$(-\omega^2 m + k) [(-\omega^2 m + k)(-\omega^2 m' + 2k) - 2k^2] = 0$$

$$(-\omega^2 m + k) [\omega^2 m m' \omega^2 - \omega^2 (m 2k + m' k)] = 0$$

$$(-\omega^2 m + k) \omega^2 [\omega^2 m m' - (m 2k + m' k)] = 0$$

$$\boxed{\omega_1^2 = k/m} \quad \boxed{\omega_2^2 = 0} \quad \boxed{\omega_3^2 = \frac{k}{m} \left(2 \frac{m}{m'} + 1 \right)} = \frac{k}{m} (2 + \frac{m}{m'})$$

$$\omega_1^2 = k/m \quad \omega_2^2 = 0 \quad \omega_3^2 = \frac{k}{m} \left(2 \frac{m}{m'} + 1 \right) = \frac{k}{m'} \left(2 + \frac{m'}{m} \right)$$

l. v. npr. 3:

$$\begin{pmatrix} -k \frac{2m}{m'} & -k & 0 \\ -k & -\frac{m'}{m} k & -k \\ 0 & -k & -k \frac{2m}{m'} \end{pmatrix} =$$

$$\underline{a}_3 = \left(1, -\frac{2m}{m'}, 1 \right) c$$

$$\underline{a}_3^T T \underline{a}_3 = c^2 \left(m + 4 \frac{m^2}{m'} + m \right) = 1 \quad c = \frac{1}{\sqrt{2m + 4m^2/m'}}$$

$$\underline{a}_3^T = \left(1, -\frac{2m}{m'}, 1 \right) \frac{1}{\sqrt{2m + 4m^2/m'}}$$

$$\underline{a}_1^T = \frac{(1, 1, 1)}{\sqrt{2m + m'}}$$

$$\underline{a}_2^T = \frac{(1, 0, -1)}{\sqrt{2m}}$$

2. o kombinacija uganjenosti in ortogonalnostne relacije

1. translacija (gibanje težišča)

$$\underline{a}_1^T = (1, 1, 1) / c_1$$

$$\underline{V} (1, 1, 1) = 0 \Rightarrow \omega_1^2 = 0$$

2. m_2 miruje, težišče miruje

$$\underline{a}_1^T = (1, 0, -1) c_2 \quad (\tilde{a}_1, 0, 0) \cdot (1, 1, 1) = 0 \Rightarrow a = -b$$

$$3. \underline{a}_3 = (\tilde{a}_1, \tilde{a}_2, \tilde{a}_3)$$

$$\underline{a}_3^T T \underline{a}_3 = 0 \Rightarrow \tilde{a}_1 = \tilde{a}_3$$

$$(\tilde{a}_1, \tilde{a}_2, \tilde{a}_1)^T \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = 0$$

$$m \tilde{a}_1 + m' \tilde{a}_2 + m \tilde{a}_1 = 0$$

$$\begin{aligned} & = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ m \tilde{a}_1 + m' \tilde{a}_2 + m \tilde{a}_3 &= 0 \\ \tilde{a}_2 &= -\frac{2m}{m'} \tilde{a}_1 \\ \underline{a_3^T} &= \left(1, -\frac{2m}{m'}, 1 \right) \end{aligned}$$

Lagrang. v. norm. abh.iki

$$L = \frac{1}{2} \left[\dot{d}_1^2 + \left(\dot{d}_2^2 - \frac{k}{m} d_2^2 \right) + \dot{d}_3^2 - \frac{k}{m} (2m'/m + 1) d_3^2 \right]$$

Splajna meš.iker

$$\begin{aligned} (x_1, x_2, x_3)^T(t) &= \underline{a_1} (c_1 + \tilde{c}_1 t) \\ &+ \underline{a_2} (c_2 \cos \omega_2 t + \tilde{c}_2 \sin \omega_2 t) \\ &+ \underline{a_3} (c_3 \cos \omega_3 t + \tilde{c}_3 \sin \omega_3 t) \end{aligned}$$

Zuč. pogoj

$$x(t=0) = (0, 0, 0)^T; \quad c_1 = c_2 = c_3 = 0$$

$$\dot{x}(t=0) = (v_0, 0, 0)^T; \quad (v_0, 0, 0)^T = \underline{a_1} \tilde{c}_1 + \underline{a_2} \tilde{c}_2 \omega_2 + \underline{a_3} \tilde{c}_3 \omega_3$$

$$\underline{a_1^T} \underline{I} \begin{pmatrix} v_0 \\ 0 \\ 0 \end{pmatrix} = \tilde{c}_1 = \frac{m}{\sqrt{2m+m'}} v_0$$

$$\underline{a_2^T} \underline{I} \begin{pmatrix} v_0 \\ 0 \\ 0 \end{pmatrix} = \tilde{c}_2 \omega_2 = \frac{m v_0}{\sqrt{2m}}; \quad \tilde{c}_2$$

$$\underline{a_3^T} \underline{I} \begin{pmatrix} v_0 \\ 0 \\ 0 \end{pmatrix} = \tilde{c}_3 \omega_3 = \frac{m v_0}{\sqrt{2m + 4m^2/m'}}$$

$$\begin{aligned} (x_1, x_2, x_3)(t) &= \frac{1}{\sqrt{2m+m'}} \frac{m}{\sqrt{2m+m'}} v_0 t (1, 1, 1) \\ &+ \frac{1}{\sqrt{2m}} \frac{m v_0}{\sqrt{2m}} (1, 0, -1) \left(\frac{\sqrt{m}}{\sqrt{k}} \right) \sin(\omega_2 t) \end{aligned}$$

$$+ \frac{1}{\sqrt{2m + \frac{4m^2}{m'}}} \frac{mv_0}{\sqrt{2m + \frac{4m^2}{m'}}} \frac{1}{\omega_3} \left(1 - \frac{2m}{m'} \right) \sin(\omega_3 t)$$

$$\underline{x} = \tilde{c}_1 t \underline{a}_1 + \tilde{c}_2 \sin \omega_2 t \underline{a}_2 + \tilde{c}_3 \sin \omega_3 t \underline{a}_3$$

energijski v lastnosti ravninik.

$$E_1 = \frac{\tilde{c}_1^2}{2} =$$

$$E_2 = \frac{\omega_2^2 \tilde{c}_2^2}{2} = \frac{mv_0^2}{4}$$

$$= \frac{m^2}{2(2m + m')} v_0^2$$

$$E_3 = \frac{m^2 v_0^2}{2(2m + \frac{4m^2}{m'})}$$

$$E_1 + E_2 + E_3 = \frac{m^2 v_0^2}{2} \left[\frac{1}{2m + m'} + \frac{1}{2m} + \frac{1}{2m + \frac{4m^2}{m'}} \right]$$

$$= \frac{m v_0^2}{2} \left[\frac{1}{2 + \mu} + \frac{1}{2} + \frac{1}{2 + \frac{4}{\mu}} \right] =$$

$$= \frac{m v_0^2}{2} \left[\frac{4 + 8/\mu + (2 + \mu)(2 + 4/\mu) + 4 + 2\mu}{(4 + 2\mu)(2 + 4/\mu)} \right]$$

$$= \frac{m v_0^2}{2} \left[\frac{1/\mu (4 + 2\mu) [2 + (2 + \mu) + \mu]}{(2 + 4/\mu)(4 + 2\mu)} \right]$$

$$= \frac{m v_0^2}{2}$$