

## The integral of a vector field $a(x)$ on a sphere

Let  $a = a^\mu \gamma_\mu = a^\mu e_\mu^a \gamma_a$  be a vector field. Here  $\gamma_\mu$  are coordinate basis vectors, whilst  $\gamma_a$  are local orthonormal basis vectors.

Let us consider the integral

$$\bar{a} = \int d^2x \sqrt{|g|} a^\mu e_\mu^a \gamma_a = \int d\mathcal{G} d\varphi r^2 \sin \mathcal{G} a^\mu e_\mu^a \gamma_a \quad (1)$$

and insert the following ansatz for the zweibein field and its reciprocal

$$e_\mu^a = \begin{pmatrix} r \cos \varphi, & r \sin \varphi \\ -r \sin \mathcal{G} \sin \varphi, & r \sin \mathcal{G} \cos \varphi \end{pmatrix} \quad e^\mu_a = \frac{1}{r} \begin{pmatrix} \cos \varphi, & \sin \varphi \\ -\frac{\sin \varphi}{\sin \mathcal{G}}, & \frac{\cos \varphi}{\sin \mathcal{G}} \end{pmatrix}$$

$$\mu = 0, 1, 2, 3; \quad a = \bar{0}, \bar{1}, \bar{2}, \bar{3}$$

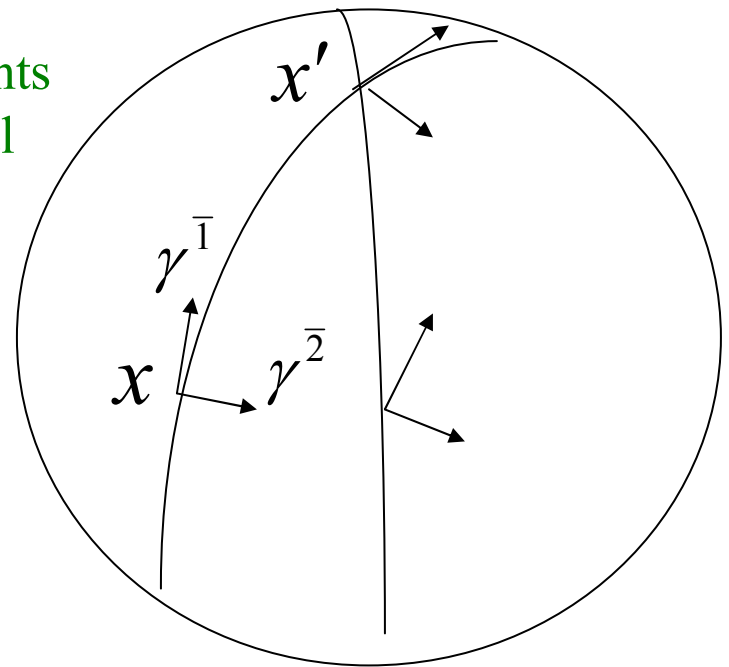
The orthonormal frame vectors are  $\gamma^a = e_{\mu}^a \gamma^{\mu}$

Explicitly we have

$$\gamma^{\bar{1}} = r \left( \cos \varphi \gamma^1 - \sin \vartheta \sin \varphi \gamma^2 \right)$$

$$\gamma^{\bar{2}} = r \left( \sin \varphi \gamma^1 + \sin \vartheta \cos \varphi \gamma^2 \right)$$

Orthonormal vectors are rotated at different points on the sphere in such a way that the orthonormal frame at point  $x$  is parallel to the orthonormal frame at a fixed chosen point  $x'$  (parallel along the geodesic joining the two points). If we let the point  $x$  vary, then the orthonormal frames at different points  $x$  are **not** parallel to each other, they are only all parallel to the frame at a chosen fixed point  $x'$ .



We can represent vectors  $\gamma^a = (\gamma^{\bar{1}}, \gamma^{\bar{2}})$  by matrices which are constant on the sphere .

The integral now reads

$$\bar{a} = \int d\mathcal{G} d\varphi r^2 \sin \mathcal{G} \left[ \left( a^1 r \cos \varphi - a^2 r \sin \mathcal{G} \sin \varphi \right) \gamma_{\bar{1}} + \left( a^1 r \sin \varphi + a^2 r \sin \mathcal{G} \cos \varphi \right) \gamma_{\bar{2}} \right]$$

If we take constant components  $a^1, a^2$  in the coordinate frame, the result of the integrations is zero. This result makes sense, because at various points  $x$  the components  $a^a$  have different orientations with respect to the orthonormal frame. When we parallel transport the frame and the vector field  $a$  from  $x$  into a chosen point  $x'$ , then at the latter point we have vectors of all possible orientations, and all those vectors are then summed together. So we obtain zero for the domain of point  $x$  covering the entire sphere. For the integration over a smaller domain we may obtain a non vanishing result.

However, the integral is defined with respect to a chosen zweibein. If we take a different zweibein the result will change.

Our choice of the zweibein is such that, in the limit of the transition to a flat space, it coincides with the choice of zweibein in the definition of the vector integral in flat space.

## The integral of a vector field $a(x)$ in flat 2-space

We will now demonstrate that even in flat space the vector integral depends on choice of vielbein (zweibein in our 2-dimensional example).

Let us consider

$$\bar{a} = \int d^2x \sqrt{|g|} a^\mu e_\mu^a \gamma_a \quad (1)$$

Choosing the cartesian coordinates we have  $d^2x = dx dy$

I. Let us first take

$$e_\mu^a = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

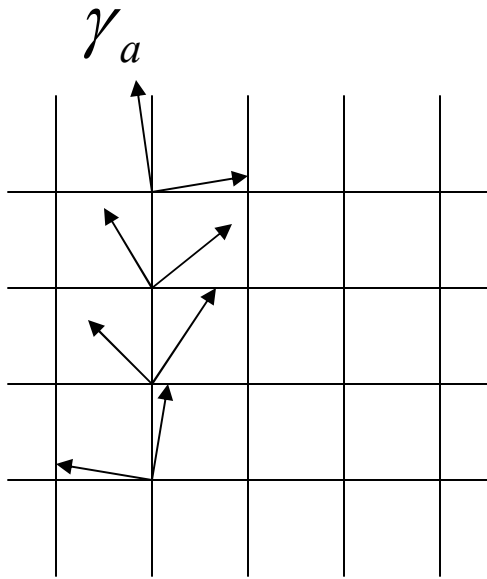
Then the local frame  $\gamma_a$  coincides with the coordinate frame  $\gamma_\mu$  which means that  $\gamma_{\bar{1}} = \gamma_1$  and  $\gamma_{\bar{2}} = \gamma_2$ . The integral (1) reads

$$\bar{a} = \int dx dy (a^1 \gamma_{\bar{1}} + a^2 \gamma_{\bar{2}})$$

This is just the usual expression for the vector integral in flat space.

II. Alternatively, we can take

$$e_{\mu}^a = \begin{pmatrix} \cos \alpha(x, y), & \sin \alpha(x, y) \\ -\sin \alpha(x, y), & \cos \alpha(x, y) \end{pmatrix}$$



The frame field  $\gamma_a = e_a^{\mu} \gamma_{\mu}$

depends on position  $x, y$ . In every point  $x, y$  the local vectors  $\gamma_a = (\gamma_{\bar{1}}, \gamma_{\bar{2}})$  are rotated for a different angle  $\alpha(x, y)$  with respect to the coordinate frame vectors  $\gamma_{\mu}$  (which are tangent to the coordinate lines). We take cartesian coordinates.

The integral of a vector field over a domain in 2-space reads

$$\bar{a} = \int dx dy [(a^1 \cos \alpha + a^2 \sin \alpha) \gamma_{\bar{1}} + (-a^1 \sin \alpha + a^2 \cos \alpha) \gamma_{\bar{2}}]$$

Let us take for example  $a^1 \neq 0, a^2 = 0$

Then we obtain

$$\bar{a} = \int dx dy [(a^1 \cos \alpha) \gamma_{\bar{1}} - (a^1 \sin \alpha) \gamma_{\bar{2}}]$$

1) Let us choose  $\alpha(x, y) = \omega x$   
and let us write  $a^1 \equiv a_x$ ,  $a^2 \equiv a_y$

$$\begin{aligned} \bar{a} &= \int dx dy [(a_x \cos \omega x) \gamma_{\bar{1}} - (a_x \sin \omega x) \gamma_{\bar{2}}] \\ &= \pi a_x [(\sin \omega x) \gamma_{\bar{1}} + (\cos \omega x) \gamma_{\bar{2}}] \Big|_0^\pi \\ &= 2 \pi a_x \gamma_{\bar{2}} \quad \text{for } \omega = 1 \end{aligned}$$

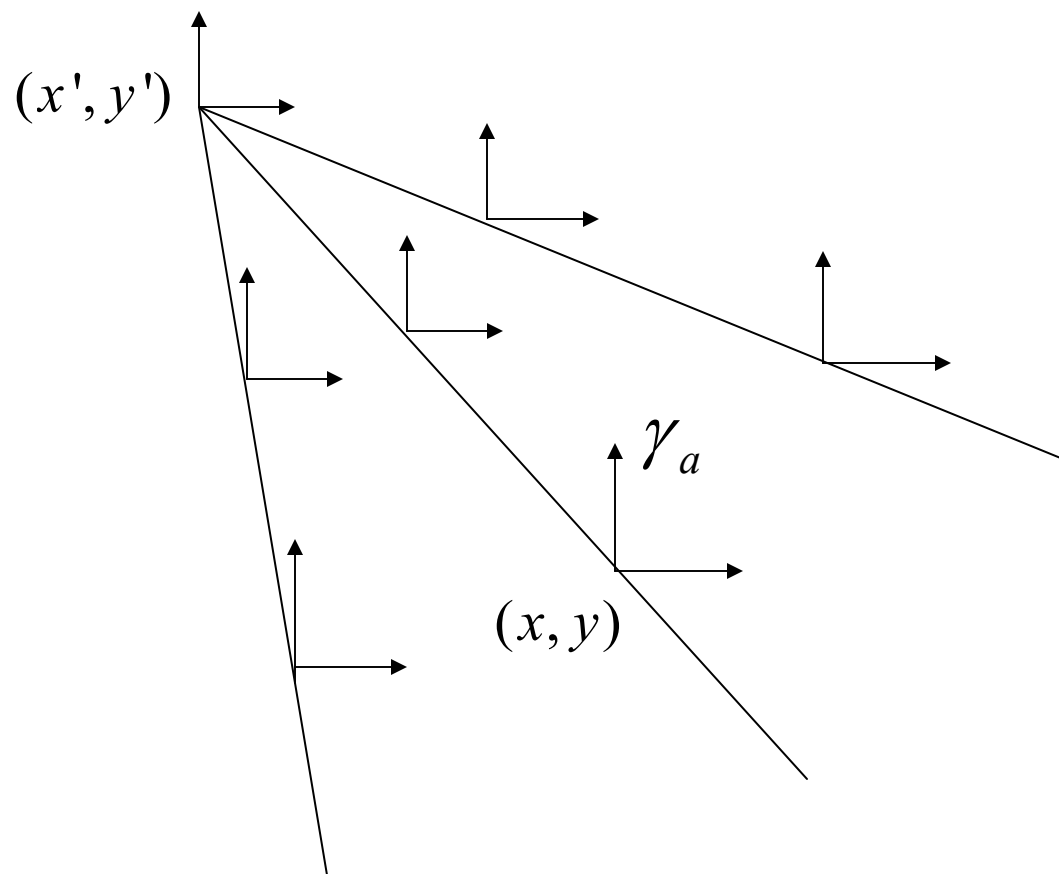
2) Let us choose  $\alpha(x, y) = 0$

$$\bar{a} = \int_0^\pi dx \int_0^\pi dy a^1 \gamma_{\bar{1}} = \pi^2 a_x \gamma_{\bar{1}}$$

The integral depends on choice of  $e_\mu^a(x, y)$ . Any choice is possible in principle.

There is a choice which is very convenient and is normally used:

We take  $e_{\mu}^a$  such that the local orthonormal frame vectors at variable points  $(x,y)$  are parallel to the local frame vectors in a given fixed point  $(x',y')$ . Local frame vectors need not coincide with coordinate frame vectors; they only need to be parallel in the above sense.



In flat space it happens that such a parallelism coincides with the global parallelism (the local frames at all points can be chosen such that they are all parallel to each other).

When going from flat to curved space the global parallelism is not preserved. We have seen that the latter property is not needed. What we need is that at all points within a chosen domain on a manifold the local orthonormal frames are parallel to a local orthonormal frame at a chosen fixed point  $x'$ . Such condition, used in the definition of the flat space vector integral can be preserved in curved space, and can be used for the definition of the vector integral in curved space. If we then make a gradual transition so that a curved space approaches flat space (curvature decreases, e.g., the radius of our sphere is becoming larger and larger) then the integral of a vector field over a finite area domain around a chosen fixed point  $x'$  approaches the usual definition of the flat space vector integral .