

$$P_- = |\langle \psi_- | \psi_+(t) \rangle|^2$$

$\psi_+(t)$

$$P_+ = |\langle \psi_+ | \psi_+(t) \rangle|^2 = |\langle \psi(0) | \psi(t) \rangle|^2$$

↳ verjetnost, da je v stanju ψ_+

$$|\psi_+(t)\rangle = \frac{1}{\sqrt{2}} (e^{-i\omega_1 t} |1\rangle + e^{-i\omega_2 t} |2\rangle)$$

$$P_- = \left| \frac{1}{\sqrt{2}} (e^{-i\omega_1 t} + e^{-i\omega_2 t}) \right|^2 = \cos^2 \frac{\omega_2 - \omega_1}{2} t = 1 - P_+$$

→ čeprav je ne začetku le $|\psi_+\rangle$,
 a časom postane mešanica $|\psi_+\rangle$
 in $|\psi_-\rangle$. Ker $|\psi_+\rangle$ NI LASTNO stanje!

↳ verjetnost oscilira = UTRIPANJE

Simetrije H

Hamiltonova f. ima lahko simetrije, kar je lepo.

1 • operator parnosti P (masedi refleksijo prostora) $\vec{r} \rightarrow -\vec{r}$
 $P f(\vec{r}) = f(-\vec{r})$

1D: $x \rightarrow -x$

• $P f(x) = f(-x) = \lambda f(x)$ če $\lambda = \begin{cases} +1 & \text{soda } f \\ -1 & \text{liha } f \end{cases}$ lahko pa λ ni ne 1 ne -1...

• $(P \frac{\partial^2}{\partial x^2}) f(x) = \frac{\partial^2}{\partial (-x)^2} f(x) = \frac{\partial^2}{\partial x^2} f(x)$

P má operatorju nas zaminu $\frac{\partial}{\partial (-x)} = -\frac{\partial}{\partial x}$ $\left[\frac{\partial^2}{\partial x^2}, P \right] = 0$

$P \frac{\partial^2}{\partial x^2} f(x) = P \left(\frac{\partial^2}{\partial x^2} f(x) \right) = \frac{\partial^2}{\partial x^2} P f(x) \Rightarrow \left[\frac{\partial^2}{\partial x^2}, P \right] = 0$
 ↳ komutirata

craj do: $P V(x) = V(x)$ Potencial je soda funkcija.

$P[V f(x)] = V P f(x) \rightarrow [P, V] = 0$

$H = \frac{p^2}{2m} + V \Rightarrow [H, P] = 0$

$P H \psi(x) = H P \psi(x)$

$H \psi(x) = E \psi(x) \Rightarrow P H \psi = H P \psi = E P \psi = E \psi(-x)$

$H \psi(-x) = E \psi(-x)$ → obema ustreza enaka energija

torimo: $\psi_{\pm}(x) = \frac{1}{\sqrt{2}} (\psi(x) \pm \psi(-x))$ → ena je soda (+),
 ene liha (-)

$P \psi_{\pm}(x) = \pm \psi_{\pm}(x)$

$\psi_+, \psi_- \rightarrow E$

⇒ če E ni degeneriran ⇒ $\psi_E(-x) = \pm \psi_E(x)$

Potem je resitev sode ali liha. Torej, ko vidiš simetrični potencial, in E ni deg, so resitve sode ali lihe.

če je degenerirano: $\psi_{1,2} = C_+^{1,2} \psi_+ + C_-^{1,2} \psi_-$ → je lin. komb sode in lihe resitve
 ↪ Prva resitev je prva lin. komb, druga resitev je druga lin. komb.

BW: Sode funkcija ima manjšo energijo. Ker $\frac{\partial^2}{\partial x^2}$ je manjši, manj je ukrivljeno, ker ni ničel, in je manjša en.

2. Obrat časa T

$$T\psi(x, t) = \psi(x, -t)$$

če: $V \neq V(t)$

$$[T, V] = 0$$

$$i\hbar \frac{\partial}{\partial t} \psi = H\psi(x, t) \quad / \text{konjug.}$$

$$-i\hbar \frac{\partial}{\partial t} \psi^* = (H\psi)^* = H^+ \psi^* = H\psi^* \quad H = H^+$$

nova spr: $\tau = -t$

$$i\hbar \frac{\partial}{\partial \tau} \tilde{\psi}(\tau) = H\tilde{\psi}(\tau)$$

sta enaki enačbi! našli smo: $\tilde{\psi}(t) = \psi(-t) = \psi^*(t)$!

$$T\psi(t) = \psi(-t) = \psi^*(t)$$

rami val: $(e^{ikx - i\omega t})^* \rightarrow$ gre v drugo smer kot $e^{ikx - i\omega t}$

časovni razvoj: $\psi(x, t) = e^{-\frac{i\hbar t}{\hbar}} \psi(x, 0)$

$$\psi(x, -t) = \dots$$

če $V \neq V(t)$ lahko dobimo stacion. resitve.

→ Posledica: $H\psi(x) = E\psi(x)$ / Stacionarno stanje, ki ni na časov. uster.

$$\text{in: } H\psi^*(x) = E\psi^*(x)$$

↳ ψ in ψ^* imata enako energijo.

* Če E ni degeneriran: $\psi^* = \psi$ ψ je realna oz: $\psi^* = \psi e^{i\varphi}$ $\psi \in \mathbb{R}$ $\varphi \in \mathbb{R}$

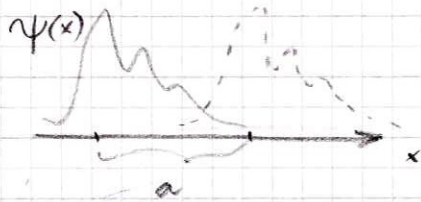
izjema: če $V=0 \rightarrow e^{ikx}, e^{-ikx}$

↳ parnata ali točna energija / drugače toni ali druga funkcija...

to je še bolj prav

→ če E je degeneriran, pa so funkcije v splošnem kompleksne.

3. translacija $U_{\vec{a}}$



$U_a \psi(x) = \psi(x-a)$ = translacija funkcije

$$= \psi(x) - a \frac{\partial \psi}{\partial x} \Big|_x + \frac{1}{2} a^2 \frac{\partial^2}{\partial x^2} \psi(x) \pm \dots + (-1)^n \frac{a^n}{n!} \frac{\partial^n}{\partial x^n} \psi(x) \pm \dots =$$

$$= \left[1 - a \frac{\partial}{\partial x} + \dots + (-1)^n \frac{a^n}{n!} \frac{\partial^n}{\partial x^n} + \dots \right] \psi(x) =$$

$$U_a \psi(x) = e^{-a \frac{\partial}{\partial x}} \psi(x)$$

$$\rightarrow -\frac{\partial}{\partial x} = \frac{(-i)(-\hbar \frac{\partial}{\partial x})}{\hbar}$$

$$U_{\vec{a}} = e^{-i \frac{\vec{a} \cdot \vec{p}}{\hbar}}$$

Operator gibalne količine je generator premika.

→ če hočeš računati s tem razvijesh Taylorja:

$$e^{-\vec{a} \cdot \nabla} = 1 - a_x \frac{\partial}{\partial x} - a_y \frac{\partial}{\partial y} + \frac{1}{2!} \left(\frac{\partial^2}{\partial x^2} + 2 \frac{\partial}{\partial x} \frac{\partial}{\partial y} + \frac{\partial^2}{\partial y^2} \right) a_x a_y + \dots$$

$$\rightarrow U_{\vec{a}+\vec{b}} = U_{\vec{a}} U_{\vec{b}} = U_{\vec{b}} U_{\vec{a}}$$

Troni grupo.

ee to pokazati:

vemo: $e^{A+B} = e^A e^B e^{-\frac{1}{2}[A,B]}$

in

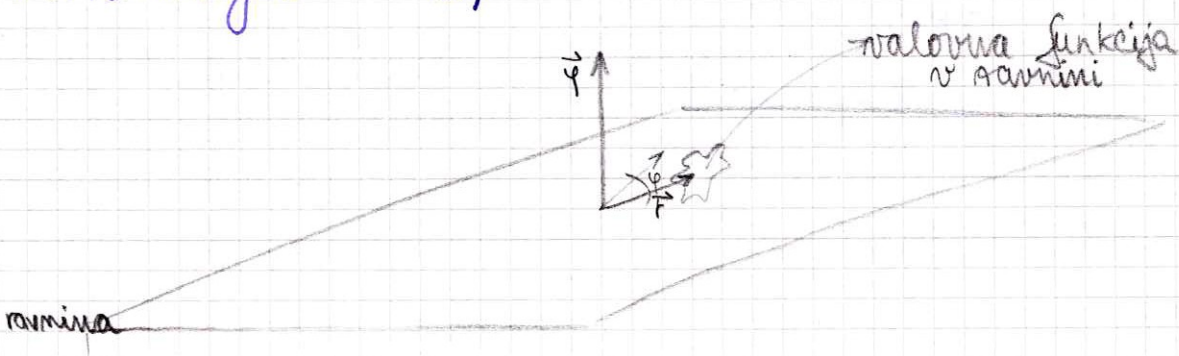
$$\begin{matrix} \vec{a} \cdot \vec{p} = A \\ \vec{b} \cdot \vec{p} = B \end{matrix}$$

D.N.

$$U_{\vec{a}}^\dagger \vec{r} U_{\vec{a}} = \vec{r} + \vec{a}$$

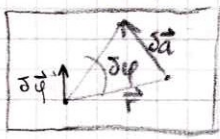
$$e^{i \frac{\vec{a} \cdot \vec{p}}{\hbar}}$$

4. rotacija $U_{\vec{\varphi}}$



$U_{\delta\varphi} f(\vec{r}) \rightarrow$ kraj bi to bilo

Ravnina od zgoraj:



$$\vec{r} + \delta\vec{a} = \vec{r}'$$

$$\delta\vec{\varphi} \times \vec{r} = \delta\vec{a}$$

$$U_{\delta\varphi} f(\vec{r}) = f(\vec{r} - \delta\vec{a})$$

$$= f(\vec{r}) - \delta\vec{a} \cdot \nabla f(\vec{r}) + \dots$$

$$= f(\vec{r}) - (\delta\vec{\varphi} \times \vec{r}) \cdot \nabla f(\vec{r}) + \mathcal{O}(\delta\varphi^2)$$

$$= f(\vec{r}) - \delta\vec{\varphi} \cdot (\vec{r} \times \nabla) f(\vec{r}) + \dots$$

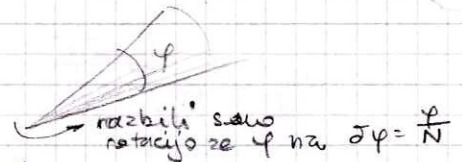
analiza:

$$(\vec{\varphi} \times \vec{r}) \cdot \nabla f = \vec{\varphi} \cdot (\vec{r} \times \nabla) f$$

$$(\vec{a} \times \vec{b}) \cdot \vec{c} = \vec{a} \cdot (\vec{b} \times \vec{c})$$

$$U_{\delta\varphi} = 1 - \frac{i\delta\vec{\varphi} \cdot (\vec{r} \times \vec{p})}{\hbar} + \mathcal{O}(\delta\varphi^2)$$

$$U_{\delta\vec{b}} = 1 - i \frac{\delta\vec{b} \cdot \vec{p}}{\hbar} \rightarrow \text{translacija} \rightarrow \text{mala}$$



$$\underbrace{U_{\delta\varphi} U_{\delta\varphi} \dots U_{\delta\varphi}}_N f(\vec{r}) = U_{\varphi}$$

spomnemo se:

$$\lim_{N \rightarrow \infty} \left(1 + \frac{x}{N}\right)^N = e^x$$

torej: $U_{\varphi} = e^{-\frac{i\vec{\varphi} \cdot \vec{L}}{\hbar}}$

$\vec{L} = \vec{r} \times \vec{p}$ je generator rotacije

↓
rotirna količina

$$\hat{L} = \hat{r} \times \hat{p} = -\hat{p} \times \hat{r}$$

memor: $[r_i, p_j] = i\hbar\delta_{ij}$

$$\vec{L} = (y p_z - z p_y, \dots)$$

↓
komutirata

Recimo: $(\vec{r} \times \vec{p})\psi = \vec{r} \times (-i\hbar\nabla)\psi$

ali: $-(\vec{p} \times \vec{r})\psi = -(-i\hbar\nabla \times \vec{r})\psi$
 $= i\hbar(\nabla\psi \times \vec{r})$

→ je res enako

medije:

$$\nabla \times f\vec{v} = f\nabla \times \vec{v} + \nabla f \times \vec{v}$$

$$\nabla \times \vec{r} = 0$$